

## **TOT Program**

### **Course Syllabus**

**Course Title: SPIKE PRIME Robotics – Python coding**

**Prerequisites: Basics of python**

**Credit hours: 15**

**Target audience: Trainers and Teachers**

#### **Course Description:**

This is a TOT course meant for trainers who are interested in teaching and training the cutting-edge LEGO Robotics platform (SPIKE PRIME) which is the substitute for the EV3 platform. Trainees are going to step up their coding skills by getting specialized hands-on training based on python language to program spike robots. Starting from the design issues such as (building-pieces uses, movement systems, structuring robots' bases ...etc.), passing by the electronic components and their uses, coding skills, and not ending with a lot of implementations and practical applications.

The Content	Duration (hour)
<p><b>Subject 1: Basics</b></p> <ul style="list-style-type: none"> <li>• Variables &amp; Data types</li> <li>• General purposes functions</li> <li>• Numeric Operations</li> <li>• String Operations</li> <li>• Logic Operations</li> <li>• Implementations</li> </ul> <p><b>Subject 2: Control Statements</b></p> <ul style="list-style-type: none"> <li>• (if) statement</li> <li>• (for) statement</li> <li>• (while) statement</li> <li>• Nested loop</li> <li>• Implementations</li> </ul> <p><b>Subject 3: Lists and Tuples</b></p> <ul style="list-style-type: none"> <li>• 1D &amp; 2D lists</li> <li>• 1D tuples</li> <li>• Methods in use</li> <li>• Implementations</li> </ul> <p><b>Subject 4: Utilizing The Hub</b></p> <ul style="list-style-type: none"> <li>• Modules, submodules, and methods in use</li> <li>• Implementations</li> </ul> <p><b>Subject 5: Straight movement &amp; Relative position</b></p> <ul style="list-style-type: none"> <li>• Modules, submodules, and methods in use</li> <li>• Synchronous(p) commands vs Asynchronous(a) commands</li> <li>• Asynchronous commands strategy1</li> <li>• Implementations</li> <li>• Building Custom Functions</li> </ul> <p><b>Subject 6: Rotation around the z-axis</b></p> <ul style="list-style-type: none"> <li>• Motion (gyro) sensor</li> <li>• Modules, submodules, and methods in use</li> <li>• Constant Motor-speed technique</li> <li>• Implementations</li> </ul>	16

## Subject 7: Sensors Operation

- The Force sensor
- The Distance sensor
- The Color sensor
- Modules, submodules, and methods in use
- Implementations

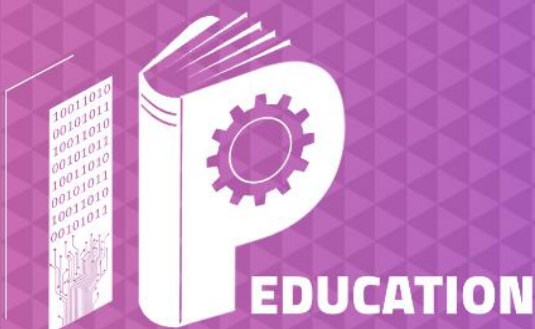
**Learning Objectives:** By the end of this course, trainees will:

### 1. Knowledge and Understanding

- Understand the basics and fundamentals of text-based coding through python language.
- Deeply, understand the required programming skills to use in practical implementations such as programming a robot.
- Comprehend the framework of writing a "clean" functional piece of code.

### 2. Skills and capabilities:

- Write simple to mid-levelled pieces of code.
- Use many programmatic commands and programming skills to control and program spike prime robots to perform various missions.
- Develop and effectively employ the skill of problem-solving, to find different programmatic solutions, many of thinking approaches as well.
- Acquire and develop a bunch of relevant engineering skills and practices.



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